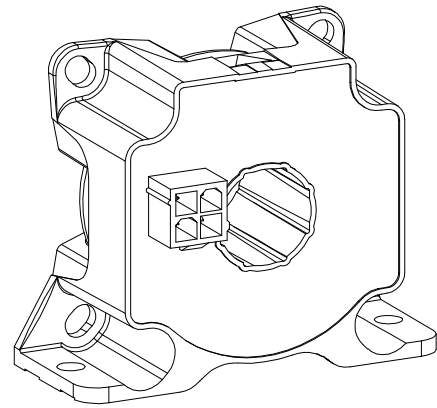
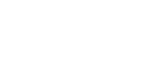


For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



## Features

- Bipolar and insulated current measurement
- Current output
- Closed loop (compensated) current transducer
- Panel mounting.

## Special Features

- $I_{PN} = 100 \text{ A}$
- $I_{PM} = 0 \dots \pm 200 \text{ A}$
- $N_S = 1000$  turns
- Connection to secondary circuit on MOLEX Mini-Fit Jr. 5566 (gold plated).

## Advantages

- High accuracy
- Very low offset drift over temperature.

## Applications

- Single or three phase inverters
- Propulsion and braking choppers
- Propulsion converters
- Auxiliary converters
- Battery chargers
- Substations.

## Standards

- EN 50121-3-2: 2015
- EN 50155: 2017
- IEC 62497-1: 2010
- UL 508: 2013.

## Application Domain

- Railway (fixed installations and onboard).

## Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage (working) (-50 °C ... 85 °C)	$\pm U_{C \max}$	V	$\pm 15.75$
Maximum primary conductor temperature	$T_{B \max}$	°C	100
Maximum steady state primary current (-50 °C ... 85 °C)	$I_{P N \max}$	A	100

Stresses above these ratings may cause permanent damage.  
Exposure to absolute maximum ratings for extended periods may degrade reliability.

## UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 9

### Standards

- USR indicates investigation to the Standard for Industrial Control Equipment UL 508.
- CNR indicates investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13.

### Ratings

Parameter	Unit	Value
Primary involved potential	V AC/DC	1500
Maximum surrounding air temperature	°C	85
Primary current	A	0 ... 100
Secondary supply voltage	V DC	0 ... $\pm 15.75$
Secondary current	mA	0 ... 100

### Conditions of acceptability

When installed in the end-use equipment, with primary feedthrough potential involved of 1500 V AC/DC, consideration shall be given to the following:

- 1 - *These products must be mounted in a suitable end-use enclosure.*
- 2 - *The secondary pin terminals have not been evaluated for field wiring.*
- 3 - *Low voltage control circuit shall be supplied by an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay).*
- 4 - *Based on the temperature test performed on LF 210-S series, the primary bar or conductor shall not exceed 100 °C in the end use application.*
- 5 - *LF 210-S series shall be used in a pollution degree 2.*

### Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

**Insulation coordination**

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_d$	kV	3.5	Type test
Impulse withstand voltage 1.2/50 $\mu$ s	$U_{Ni}$	kV	7.6	
Clearance (pri. - sec.)	$d_{Cl}$	mm	7.5	Shortest distance through air
Creepage distance (pri. - sec.)	$d_{Cp}$	mm	20.2	Shortest path along device body
Application example Rated insulation RMS voltage	$U_{Nm}$	V	920	Basic insulation (interpolated) according to IEC 62497-1 CAT III, PD2
Application example Rated insulation RMS voltage	$U_{Nm}$	V	413	Reinforced insulation (interpolated) according to IEC 62497-1 CAT III, PD2
Case material	-	-	V0	According to UL 94
Comparative tracking index	$CTI$		600	

**Environmental and mechanical characteristics**

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Ambient operating temperature	$T_A$	°C	-40		85	
Ambient storage temperature	$T_S$	°C	-50		85	
Equipment operating temperature class						EN 50155: OT6
Switch-on extended operating temperature class						EN 50155: ST0
Rapid temperature variation class						EN 50155: H2
Conformal coating type						EN 50155: NA
Mass	$m$	g		75		

**RAMS data**

Parameter	Symbol	Unit	Min	Typ	Max
Useful life class					EN 50155: L4
Mean failure rate	$\bar{\lambda}$	$h^{-1}$		1/1984154	According to IEC 62380: 2004 $T_A = 40$ °C ON: 24 h/day ON/OFF: 365 cycles/year $U_C = \pm 15$ V, $I_P = 100$ A RMS

## Electrical data

At  $T_A = 25\text{ °C}$ ,  $\pm U_C = \pm 15\text{ V}$ ,  $R_M = 1\text{ }\Omega$ , unless otherwise noted.

Lines with a \* in the conditions column apply over the  $-40 \dots 85\text{ °C}$  ambient temperature range.

Parameter	Symbol	Unit	Min	Typ	Max	Conditions
Primary nominal RMS current	$I_{PN}$	A			100	*
Primary current, measuring range	$I_{PM}$	A	-200		200	*
Measuring resistance	$R_M$	$\Omega$	0 <sup>1)</sup>			* Max value of $R_M$ is given in Figure 1
Secondary nominal RMS current	$I_{SN}$	A	-0.1		0.1	*
Resistance of secondary winding	$R_S$	$\Omega$			8.5	$R_S(T_A) = R_S \times (1 + 0.004 \times (T_A + \Delta\text{temp} - 25))$ Estimated temperature increase @ $I_{PN}$ is $\Delta\text{temp} = 15\text{ °C}$
Secondary current	$I_S$	A	-0.20		0.20	*
Number of secondary turns	$N_S$			1000		
Nominal sensitivity	$S_N$	mA/A		1		
Supply voltage	$\pm U_C$	V	$\pm 11.4$		$\pm 15.75$	*
Current consumption	$I_C$	mA		$33 + I_S$ $35 + I_S$		$\pm U_C = \pm 12\text{ V}$ $\pm U_C = \pm 15\text{ V}$
Inrush current						NA (EN 50155)
Interruptions on power supply voltage class						NA (EN 50155)
Supply change-over class						NA (EN 50155)
Offset current, referred to primary	$I_O$	A	-0.15		0.15	
Temperature variation of $I_O$ , referred to primary	$I_{OT}$	A	-0.2		0.2	*
Magnetic offset current (@ $3 \times I_{PN}$ ), referred to primary	$I_{OM}$	A		$\pm 0.2$		
Sensitivity error	$\varepsilon_S$	%	-0.15		0.15	*
Linearity error	$\varepsilon_L$	% of $I_{PN}$	-0.05		0.05	*
Total error at $I_{PN}$	$\varepsilon_{tot}$	% of $I_{PN}$	-0.2 -0.2		0.2 0.2	* 25 ... 85 °C -40 ... 85 °C
RMS noise current referred to primary	$I_{no}$	mA		20		1 Hz to 100 kHz (see Figure 4)
Delay time to 10 % of the final output value for $I_{PN}$ step	$t_{D10}$	$\mu\text{s}$		< 0.5		0 to 200 A, 75 A/ $\mu\text{s}$ , $R_M = 10\text{ }\Omega$
Delay time to 90 % of the final output value for $I_{PN}$ step	$t_{D90}$	$\mu\text{s}$		< 0.5		0 to 200 A, 75 A/ $\mu\text{s}$ , $R_M = 10\text{ }\Omega$ (see Figure 2)
Frequency bandwidth	$BW$	kHz		100		$R_M = 50\text{ }\Omega$ ; -3 dB

**Note:** <sup>1)</sup> With  $\pm 15$  as power supply. Other values of minimum values according to conditions of use are given in Figure 1.

## Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval. Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.

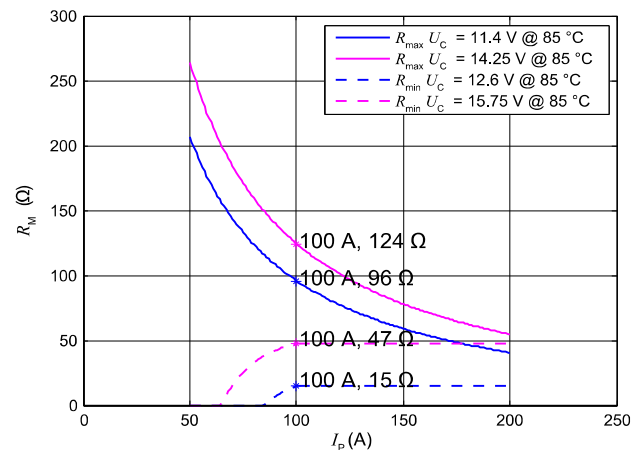
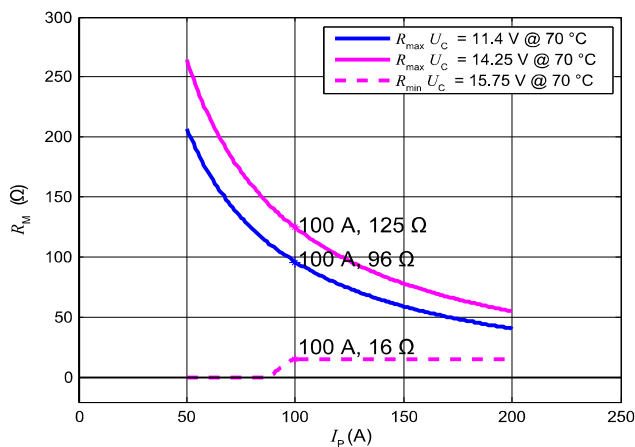


Figure 1: Maximum measuring resistance

$$R_{M \max} = N_S \times \frac{U_{C \min} - 0.3 \text{ V}}{I_P} - R_{S \max} - 4.1 \Omega$$

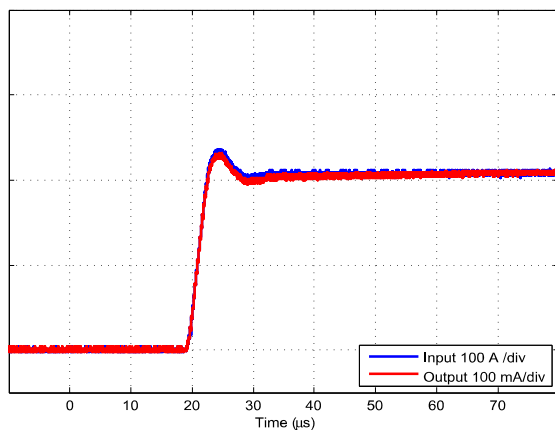


Figure 2: Typical delay time (0 to 200 A, 75 A/μs, with  $R_M = 10 \Omega$ )

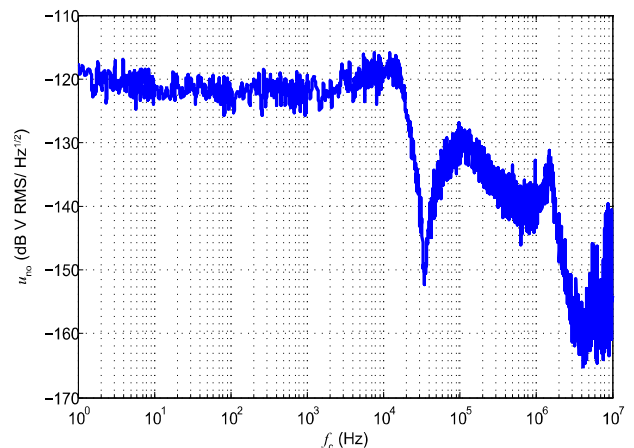


Figure 3: Typical noise voltage spectral density referred to primary  $u_{no}$  with  $R_M = 10 \Omega$

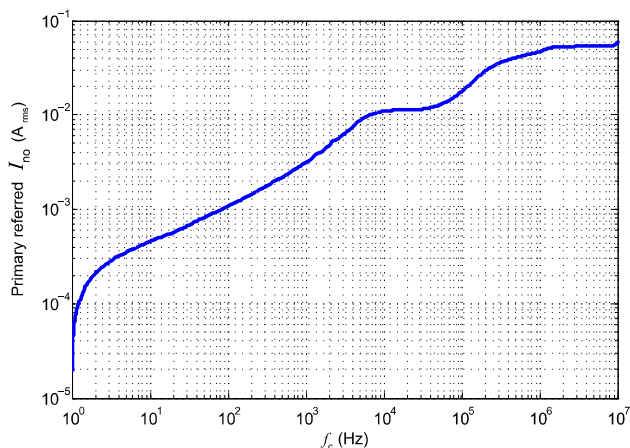


Figure 4: Typical RMS noise current referred to primary with  $R_M = 10 \Omega$

To calculate the noise in a frequency band  $f_1$  to  $f_2$ , the formula is:

$$I_{no}(f_1 \dots f_2) = \sqrt{I_{no}(f_2)^2 - I_{no}(f_1)^2}$$

with  $I_{no}(f)$  read from figure 4 (typical, RMS value).

Example:

What is the noise from  $10^3$  to  $10^6$  Hz?

Figure 4 gives  $I_{no}(10^3 \text{ Hz}) = 3 \text{ mA}$

and  $I_{no}(10^6 \text{ Hz}) = 50 \text{ mA}$ .

The output RMS noise current is therefore:

$$\sqrt{(50 \times 10^{-3})^2 - (3 \times 10^{-3})^2} = 50 \text{ mA referred to primary}$$

## Typical performance characteristics continued

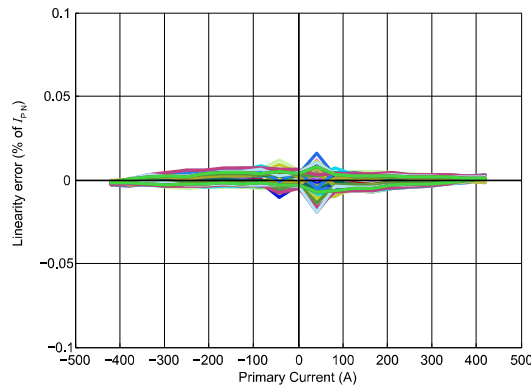


Figure 5: Linearity

## Performance parameters definition

### Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to  $I_{PM}$ , then to  $-I_{PM}$  and back to 0 (equally spaced  $I_{PM}/10$  steps).

The sensitivity  $S$  is defined as the slope of the linear regression line for a cycle between  $\pm I_{PM}$ .

The linearity error  $\varepsilon_L$  is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

### Magnetic offset

The magnetic offset  $I_{OM}$  is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range.

### Electrical offset

The electrical offset current  $I_{OE}$  is the residual output current when the input current is zero.

### Total error

The total error  $\varepsilon_{tot}$  is the error at  $\pm I_{PN}$ , relative to the rated value  $I_{PN}$ .

It includes all errors mentioned above.

### Delay times

The delay time  $t_{D10}$  @ 10 % and the delay time  $t_{D90}$  @ 90 % with respect to the primary are shown in the next figure.

Both slightly depend on the primary current  $di/dt$ .

They are measured at nominal current.

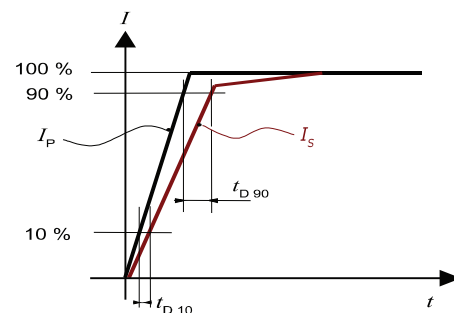


Figure 6:  $t_{D10}$  (delay time @ 10 %) and  $t_{D90}$  (delay time @ 90 %)

